

# **Advanced UVOIR Mirror Technology Development for Very Large Space Telescopes**

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# Objective

Define and initiate a long-term program to mature six inter-linked critical technologies for future UVOIR space telescope mirrors to TRL6 by 2018 so that a viable flight mission can be proposed to the 2020 Decadal Review.

- *Large-Aperture, Low Areal Density, High Stiffness Mirrors:* 4 to 8 m monolithic & 8 to 16 m segmented primary mirrors require larger, thicker, stiffer substrates.
- *Support System:* Large-aperture mirrors require large support systems to ensure that they survive launch and deploy on orbit in a stress-free and undistorted shape.
- *Mid/High Spatial Frequency Figure Error:* A very smooth mirror is critical for producing a high-quality point spread function (PSF) for high-contrast imaging.
- *Segment Edges:* Edges impact PSF for high-contrast imaging applications, contributes to stray light noise, and affects the total collecting aperture.
- *Segment-to-Segment Gap Phasing:* Segment phasing is critical for producing a high-quality temporally stable PSF.
- *Integrated Model Validation:* On-orbit performance is determined by mechanical and thermal stability. Future systems require validated performance models.

We are pursuing multiple design paths give the science community the option to enable either a future monolithic or segmented space telescope.

# Approach

Technology must enable mission capable of doing both general astrophysics and ultra-high contrast observations of exoplanets.

Outstanding team of academic, industry & government with expertise:

- UVOIR astrophysics and exoplanet characterization,
- monolithic and segmented space telescopes, and
- optical manufacturing and testing.

Integrate science & systems engineering to:

- derive engineering specifications from science measurement needs and implementation constraints;
- identify technical challenges in meeting these specifications;
- iterate between science and systems engineering to mitigate challenges; and
- prioritize the challenges.

Systematically mature TRL of prioritized challenges using

- design tools to construct analytical models and
- prototypes/test beds to validate models in relevant environments.

# Goals

Defined quantifiable goals for each of the six key technologies:

*Large-Aperture, Low Areal Density, High Stiffness Mirror Substrates:*

- make a sub-scale mirror via a process traceable to 500 mm deep mirrors

*Support System:*

- produce pre-Phase-A point designs for candidate primary mirror architectures; and
- demonstrate specific actuation and vibration isolation mechanisms

*Mid/High Spatial Frequency Figure Error:*

- ‘null’ polish a 1.5-m AMSD mirror & subscale deep core mirror to a  $< 6$  nm rms zero-g figure at the 2 C operational temperature.

*Segment Edges:*

- derive edge specifications traceable to science requirements; and
- demonstrate an achromatic edge apodization mask.

*Segment to Segment Gap Phasing:*

- develop models for segmented primary mirror performance; and
- test prototype passive and active mechanisms to control unconstrained, damped and constrained gaps to  $\sim 1$  nm rms.

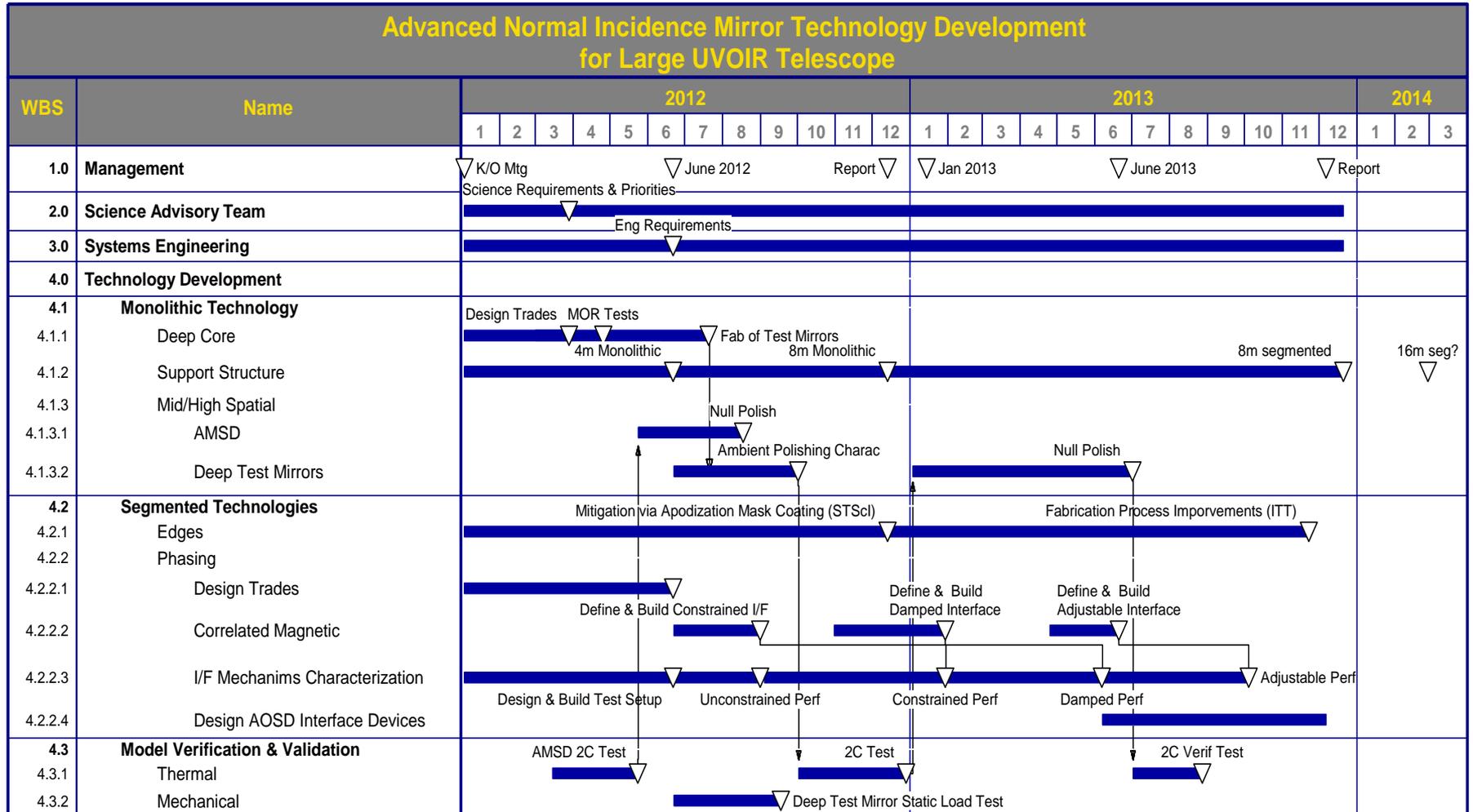
*Integrated Model Validation:*

- validate thermal model by testing the AMSD and deep core mirrors at 2 C; and
- validate mechanical models by static load test.

# Work Breakdown Structure

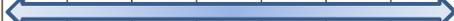
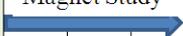
Project is managed according to WBS.

Each quantitative Milestone is scheduled.

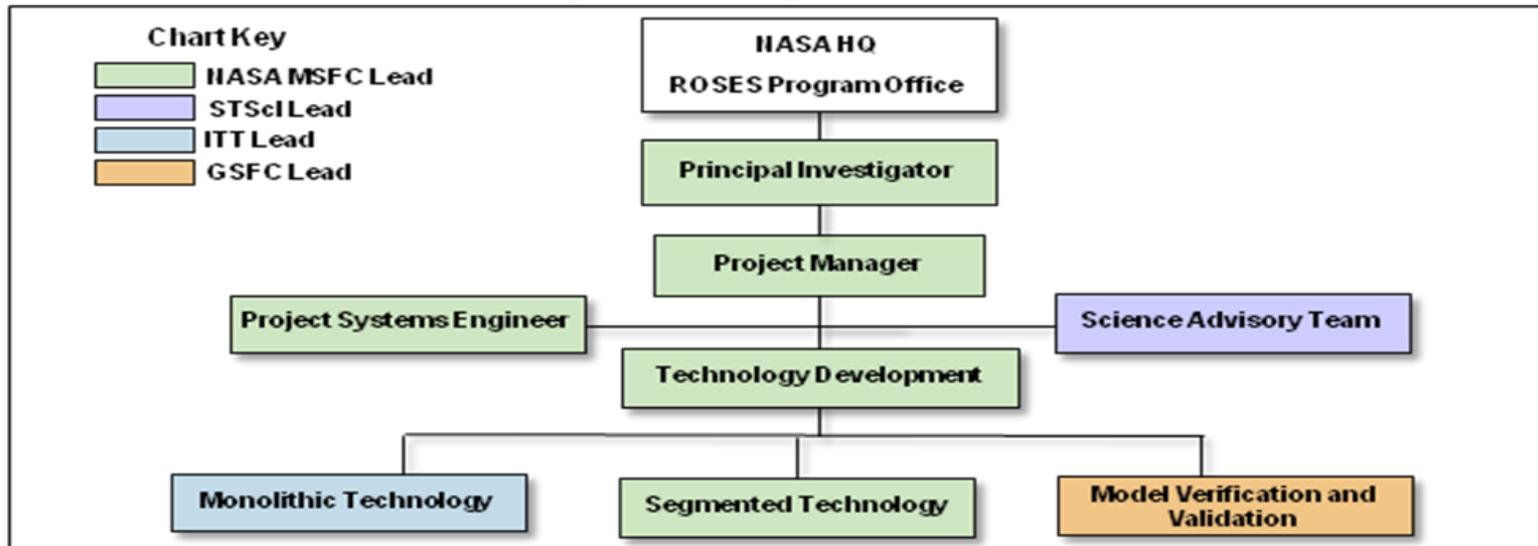


# Milestone Project

Project was rephased from 2 years to 3 years.

TASK	FY 2012			FY 2013												FY 2014								
	JUL Y	AU G	SEP	OC T	NO V	DE C	JA N	FE B	MA R	AP R	MA Y	JU N	JUL Y	AU G	SEP	OC T	NO V	DE C	JAN	FEB	MA R	AP R	MA Y	
Major Milestones																								
Large-Aperture, Low Areal Density, High Stiffness Mirror Substrates	Mirror Fabrication 																							
Support System	4m Point Design 			8m Point Design 																				
Mid/High Spatial Frequency Figure Error							Optically Process Subscale Mirror 										Optically Process AMSD 							
Segment Edges	Apodization Characterization 																							
Segment Phasing	Correlated Magnet Study 			Active Two-Stage Displacement Actuator  												 								
Integrated Model Validation				2C Test Subscale 			Load Test Subscale 									2C Test ASMD 		Load Test ASMD 						

# Project Organization



Principle Investigator		Systems Engineering		
Dr. H. Philip Stahl	MSFC	SE Lead	Dr. W. Scott Smith	MSFC
		Integrated Modeling	Gary Mosier	GSFC
Science Advisory		Engineering		
Dr. Marc Postman	STScI	ITT Project Manager	Calvin Abplanalp	ITT
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Dr. Olivier Guyon	UoA	Mechanical Analyst	TBD	ITT
Dr. John E. Krist	JPL	Mirror System Design Lead	Roger Dahl	ITT
		Optical Testing	Ron Eng	MSFC
		Structure Mechanical	William Arnold	Jacobs
		Institutional Co-I	Larry Fullerton	CMR

# WBS Task Discussion

## WBS 2.0 Science Advisory Team

Science team works with Engineering to:

- derive (and/or confirm) engineering specifications for advanced normal incidence mirrors which flow down from the astrophysical measurement needs and flow up from implementation constraints;
- collaborate with systems engineering to mitigate these challenges via architectural implementation trades; and
- prioritize which challenges should be solved first.

The Science Team has meet 4X by telecon and once face-to-face in FY12.

# WBS 3.0 Systems Engineering

## Systems Engineering working with Science:

- derives engineering mirror specifications to achieve on-orbit performance requirements;
- identifies technical challenges in meeting these specifications;
- prioritize technology development using a systems perspective to determine which technologies will yield the greatest on-orbit performance improvement; and
- define metrics, evaluate their TRL, and assess their advance.

# WBS 3.0 Systems Engineering

## Systems Engineering will

- develop thermal & mechanical models of candidate mirror systems including substrates, structures, and mechanisms;
- validate models by test of full- and subscale components in relevant thermo-vacuum environments.

## Specific analyses include:

- maximum mirror substrate size, first fundamental mode frequency (i.e., stiffness) and mass required to fabricate without quilting, survive launch, achieve stable pointing and maximum thermal time constant;
- segment edge dimensions and roll; and
- segment-to-segment gap dimensions, phasing and stability.

# WBS 4.0 Technology Development

## WBS 4.0 develops technology

- 4.1 Monolithic Mirror Technology
- 4.2 Segmented Mirror Technology
- 4.3 Model Verification and Validation

## Enables our 4 baseline options:

- 4-m monolithic mirror launched by an EELV;
- 8-m monolithic mirror launched by a HLLV;
- 8-m segmented mirror launched by an EELV; and
- 16-m segmented mirror launched by a HLLV.

Same technology can also enable 8-m on HLLV.

# WBS 4.1 Monolithic Technologies

Monolithic mirror technology is required to manufacture, test, launch, and operate a 4 or 8-m monolithic mirror also 2-m class mirror segments.

WBS 4.1 matures the 3 key monolithic mirror challenges:

- 4.1.1            Deep Core Mirror Substrate
- 4.1.2            Mirror Support Structure
- 4.1.3            Mid/High Spatial Frequency Surface Errors

## WBS 4.2 Segmented Technologies

Segmented mirror technology is required to assemble, align, phase, and operate a segmented mirror as an integrated unit to UVOIR tolerances.

WBS 4.2 matures the 2 key segmented mirror challenges:

- 4.2.1            Edge Control
- 4.2.2            Gap Phasing Control

## WBS 4.3 Model Verification & Validation

Models are required to predict on-orbit performance for pointing stability, jitter, and thermal-elastic stability, as well as vibro-acoustics and launch loads. Performance data is required to verify and validate models.

WBS 4.3 matures the 2 key modeling challenges:

- 4.3.1 Thermal Model Verification
- 4.3.2 Mechanical Model Verification

# WBS 4.1.1 Deep Core Substrate

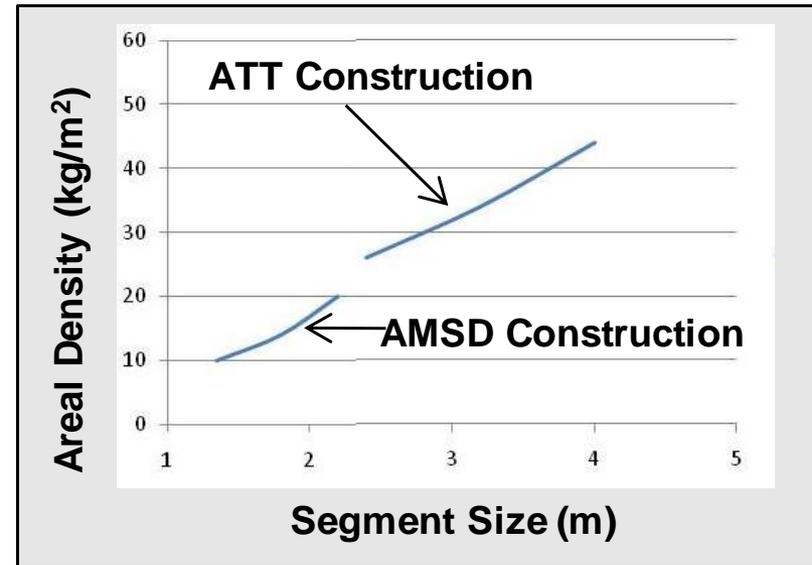
Need: 500 mm thick mirror substrate.

4 m PM requires substrate with areal density of  $<60 \text{ kg/m}^2$  &  $\sim 200 \text{ Hz}$  first mode. Analysis indicates this can be achieved with a 500 mm thick mirror. For 8-m, this is an upper thickness limit.

SOA: 300 mm deep substrates

Starting: TRL3/4

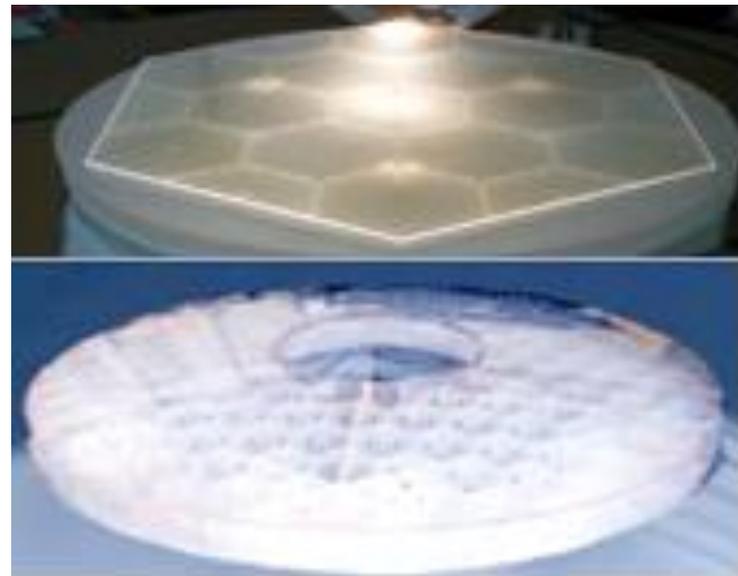
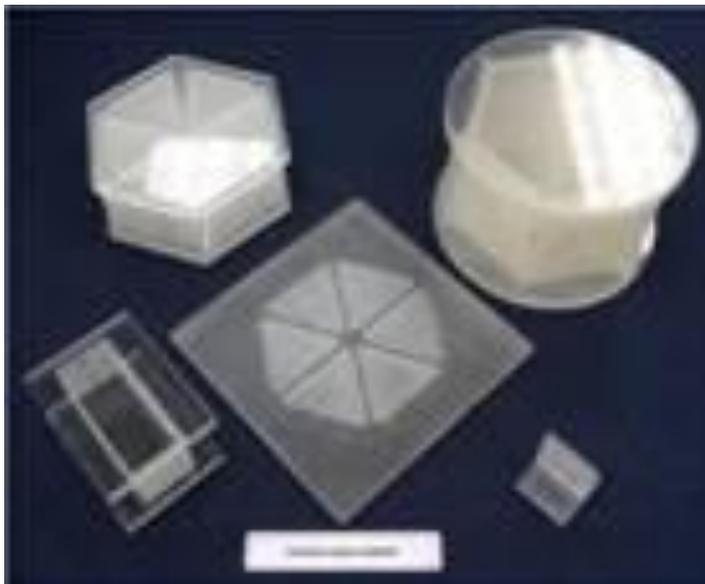
2.4 m is TRL9 (HST), Kepler is 1.4m – both are sub-scale.



## WBS 4.1.1 Deep Core Substrate

Milestone: demonstrate innovative process to make glass cores with required areal density that can be scaled to 500 mm deep.

Approach: manufacture 40 cm dia x 400 deep subscale ('cut-out' of a 4 m dia x 400 mm deep mirror) using 3 'stacked' cores with full size cells and ribs and pocket milled face and back sheets with full sized pockets, ribs and thickness.



## WBS 4.1.2 Support Structure

**Need:** System to support mirror during launch and deploy it into an on-orbit strain free state; maintain operational wavefront and pointing stability.

**SOA:** Kepler 1.4 m support system

**Starting:** TRL3/4

Kepler support system is TRL9, but it is sub-scale.

**Milestone:** Pre-Phase-A point designs for potential 4-m and 8-m monolithic primary mirrors and an 8-m segmented mirror.

**Approach:**

Design structure based on substrate designs, launch vehicle constraints and performance requirements.

Design, build & demonstrate a two-stage active strut/actuator.

## WBS 4.1.3 Mid/High Spatial Frequency

Need: < 10 nm rms surface mirror at 2C

SOA:

AMSD at <10 nm rms and ATT at <20 nm rms at 20C

Hubble, 7.8 nm rms at 20C

4m & 8m ground telescope mirrors at ~ 10 nm rms at 20C

Starting: TRL4 for 1.5 m; TRL 3 for 4 m or larger.

AMSD, ATT & HST are sub-scale & not at operational temperature.

Ground 4m & 8m mirrors are full size, but not flight areal density.

Milestone: polish traceable substrates to UVOIR tolerances at their anticipated operating temperature of 2 C.

Approach:

Create mechanical and thermal models

Test AMSD mirror at 2C and cryo-null polish via traceable process

Demonstrate on 4.1.1 sub-scale mirrors process (traceable to 2m, 4m or 8m mirrors) to polish without introducing quilting

## WBS 4.2.1 Edge Control

Need: TBD by Science and Systems Engineering

SOA: Keck is 2 mm (but substrates are 400 Hz); JWST is close to 5 mm; AMSD was 10 mm; QED & Zeeko SBIRs did 2 mm

Starting: TRL3 to 6 depending on Requirement

Milestone:

- Define Requirement

- Demonstrate apodization concept via a test article.

Approach:

- Write an amplitude apodization mask on the edge of a mirror and test its impact on edge diffraction.

## WBS 4.2.2 Gap Phase Control

Need:  $< 5$  nm rms segment to segment stability

SOA: JWST, passive, 20 nm 50 Hz rocking mode; Keck, active,  $< 20$  nm rms 50 Hz; ITT AOSD, active,  $< 10$  nm rms 30 Hz; LAMP, active, classified in Vacuum.

Starting: TRL3/4

UVOIR Requirement not achieved.

Milestone:

Demonstrate Active Strut (WBS 4.1.2)

Quantify utility of Correlated Magnetic Interfaces

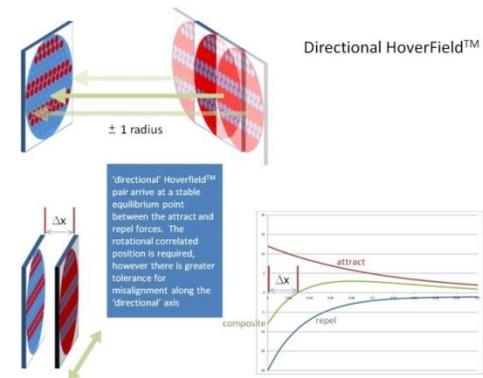
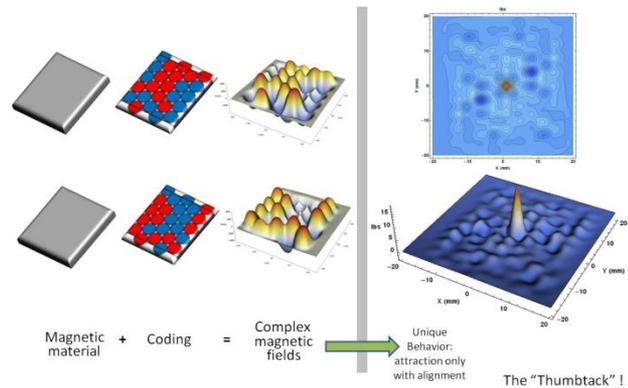
Approach: design, build and test dynamic dampening devices on sub-scale test-bed and on ITT AOSD test-bed.



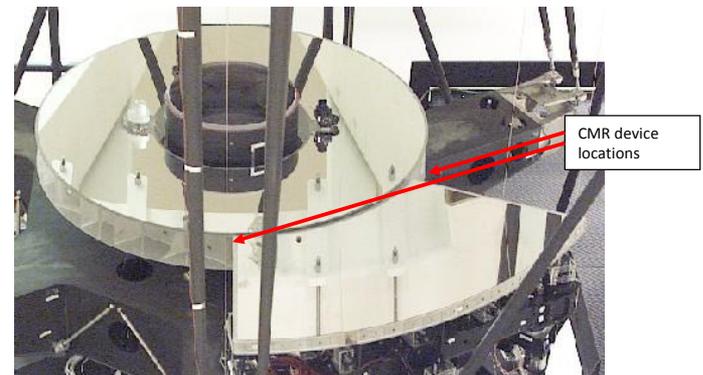
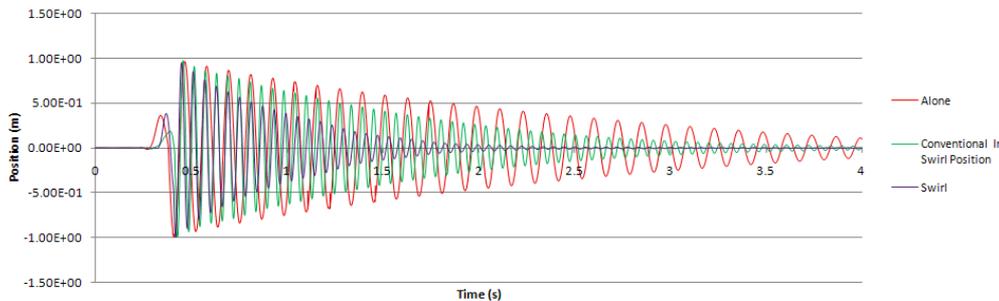
# Correlated Magnetic (CM) Interface

CMs are useful for vibration isolation & motion constraint.

CM can be designed to constrain interface to a single symmetry point; rotate about a symmetry point; or move linearly in one direction but not the orthogonal direction – similar to a mechanical flexure.



Swirl Comparison



# WBS 4.3 Integrated Modeling

Need: Predict on-orbit performance

SOA:

JWST (AMSD, Flight PMSAs, BSTA 4% match);

Air Force Structural Vibration Modeling and Verification (SVMV)

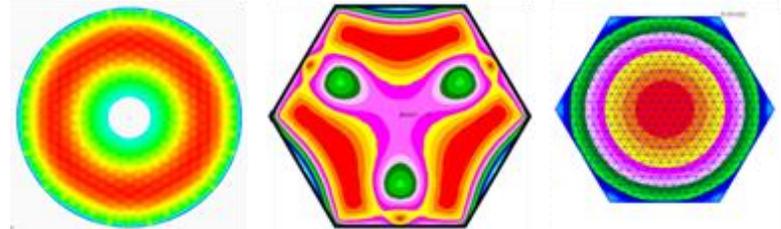
Starting: TRL4/5

UVOIR Requirement not achieved.

Milestone:

Validate Thermal Model

Validate Mechanical Model



Approach:

Thermal model predicts AMSD figure sensitivity of 5 nm rms/K.

Prediction will be validated at the MSFC XRCF. Additionally, thermal figure stability will be quantified.

Mechanical model will be validated via static load test.