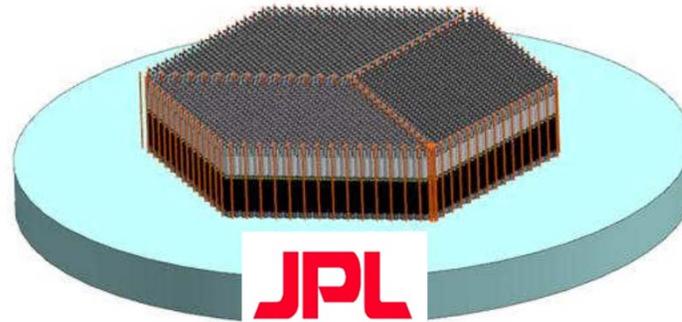
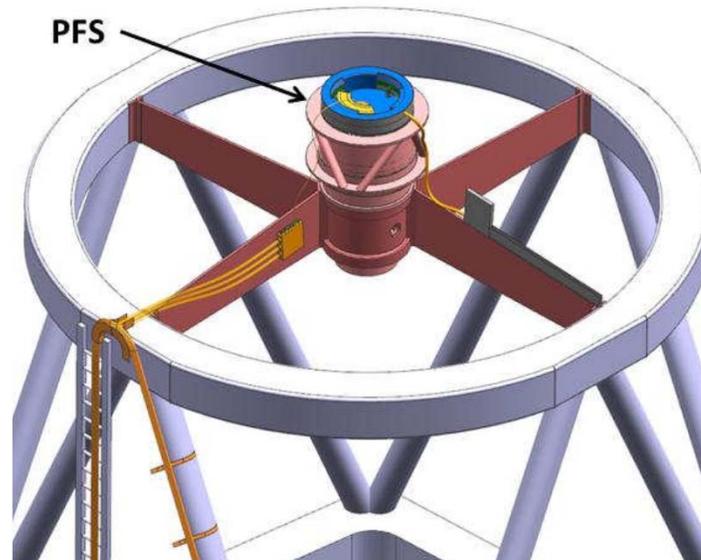


Cobra, 2-Degree of Freedom Fiber Optic Positioner for the Subaru Prime Focus Spectrograph



*David Henderson
co-CEO and CTO*



 **NEW SCALE**
TECHNOLOGIES
Ingenuously Small Motion Systems

New Scale Technologies, Inc.
121 Victor Heights Parkway
Victor NY 14564

www.newscaletech.com

- About New Scale
- Background and Acknowledgements
- System Requirements – PFS
- Selection of Piezo Motor Technology
- 2-Axis Positioner Module
- Future Work

About New Scale Technologies

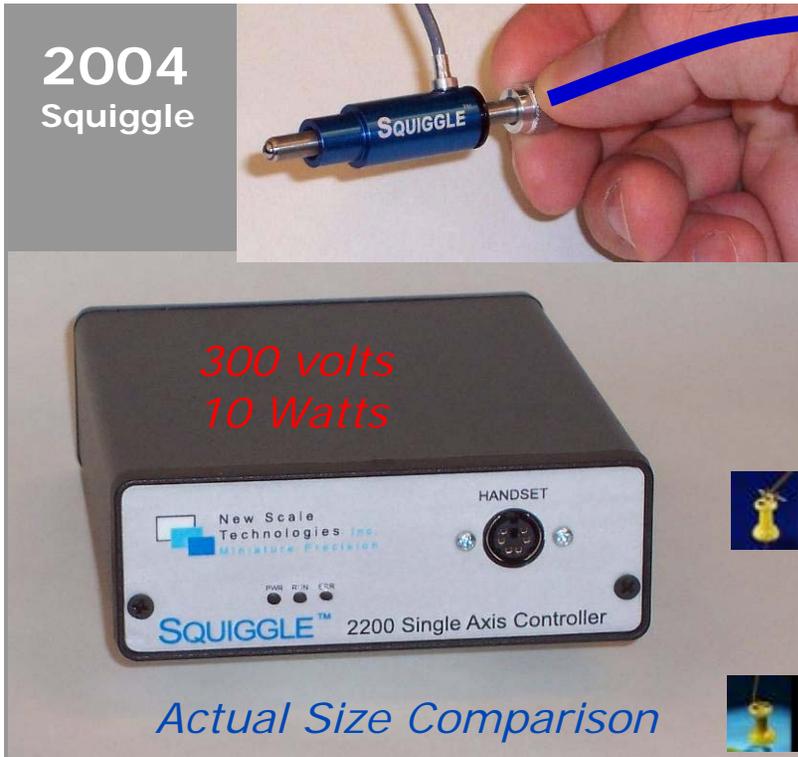
- Founded in 2002 by David Henderson
- Innovation in Tiny Piezo Motors and Micro Motion Systems
- Manufacturing and System Integration
- New Scale Delivers Motion Systems:
 - Small.....*fits in mobile phone*
 - Precise.....*micrometer movements*
 - Smart.....fully integrated, “plug and play”



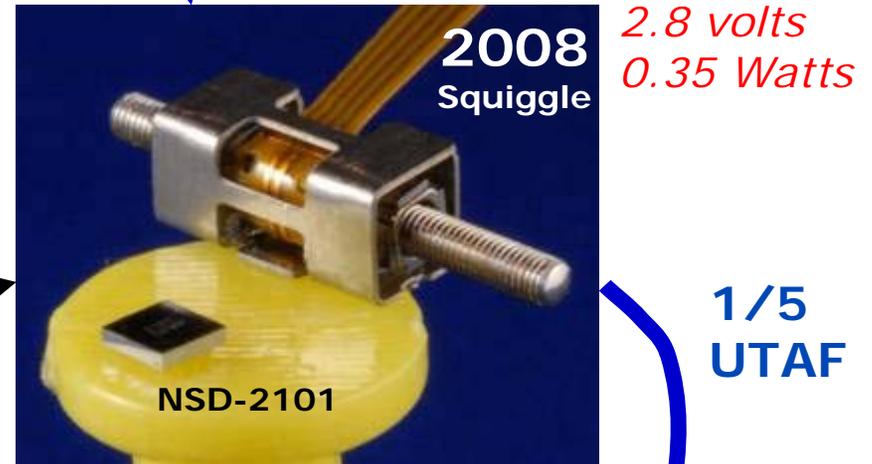
Strategic business partner		Investment, ASIC's, Sales Support
----------------------------	---	-----------------------------------

Licensed manufacturing partners	<p>TDK-EPC (EPCOS)</p> <p>UTAF Actuator Motor and Modules</p> <p>SQUIGGLE Advanced piezo ceramics</p>	<p>Tier 1 Camera Module Companies</p> <p>UTAF Actuator Modules</p>	<p>TAMRON</p> <p>Perfecting the Art of Electronics</p> <p>ALPS</p> <p>SQUIGGLE motors</p>
---------------------------------	--	--	---

About New Scale ...Miniaturization



1/100 Squiggle



1/500 Smaller Motor
1/10,000 Smaller Drive
1/100 Lower Voltage
1/100 Lower Power

Background and Acknowledgements

Developments in high-density Cobra fiber positioners for the Subaru Telescope's Prime Focus Spectrometer

Charles D. Fisher^{*a}, David F. Braun^a, Joel V. Kaluzny^a, Michael D. Seiffert^a, Richard G. Dekany^b,
Richard S. Ellis^c, Roger M. Smith^c

^aJet Propulsion Laboratory/California Institute of Technology, 4800 Oak Grove Dr., Pasadena, CA 91109 USA; ^bCaltech Optical Observatories, 1201 East California Blvd., Pasadena, CA 91125 USA;

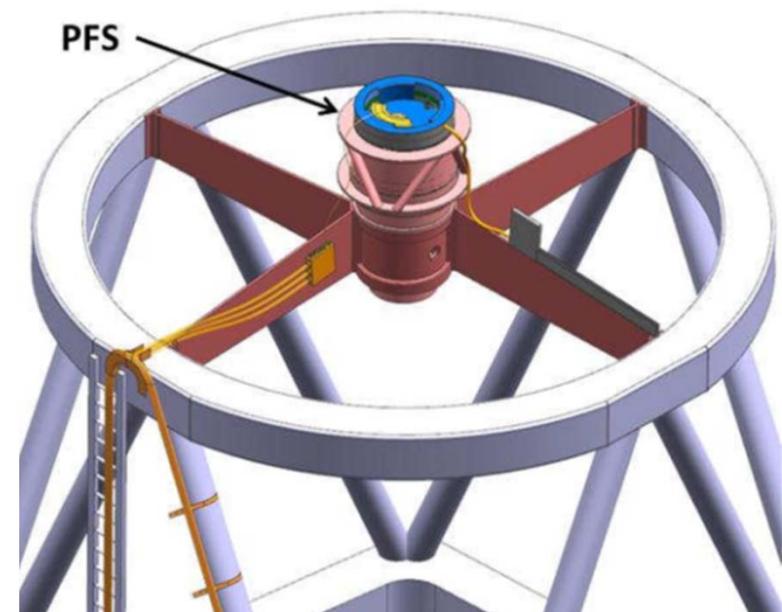
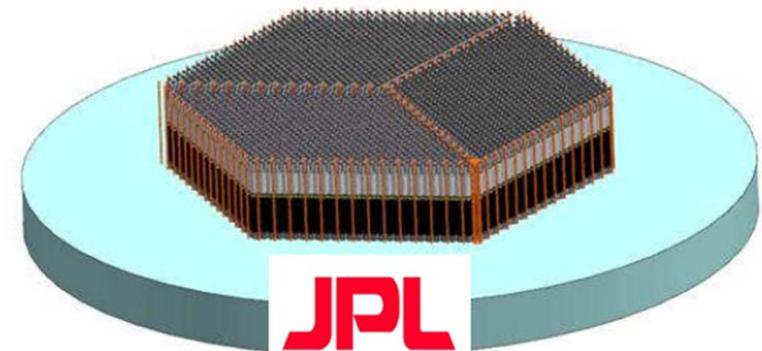
^cCalifornia Institute of Technology, 1201 E. California Blvd., Pasadena, CA 91125 USA

Presented this month in Amsterdam at SPIE Astronomical Telescopes + Instrumentation

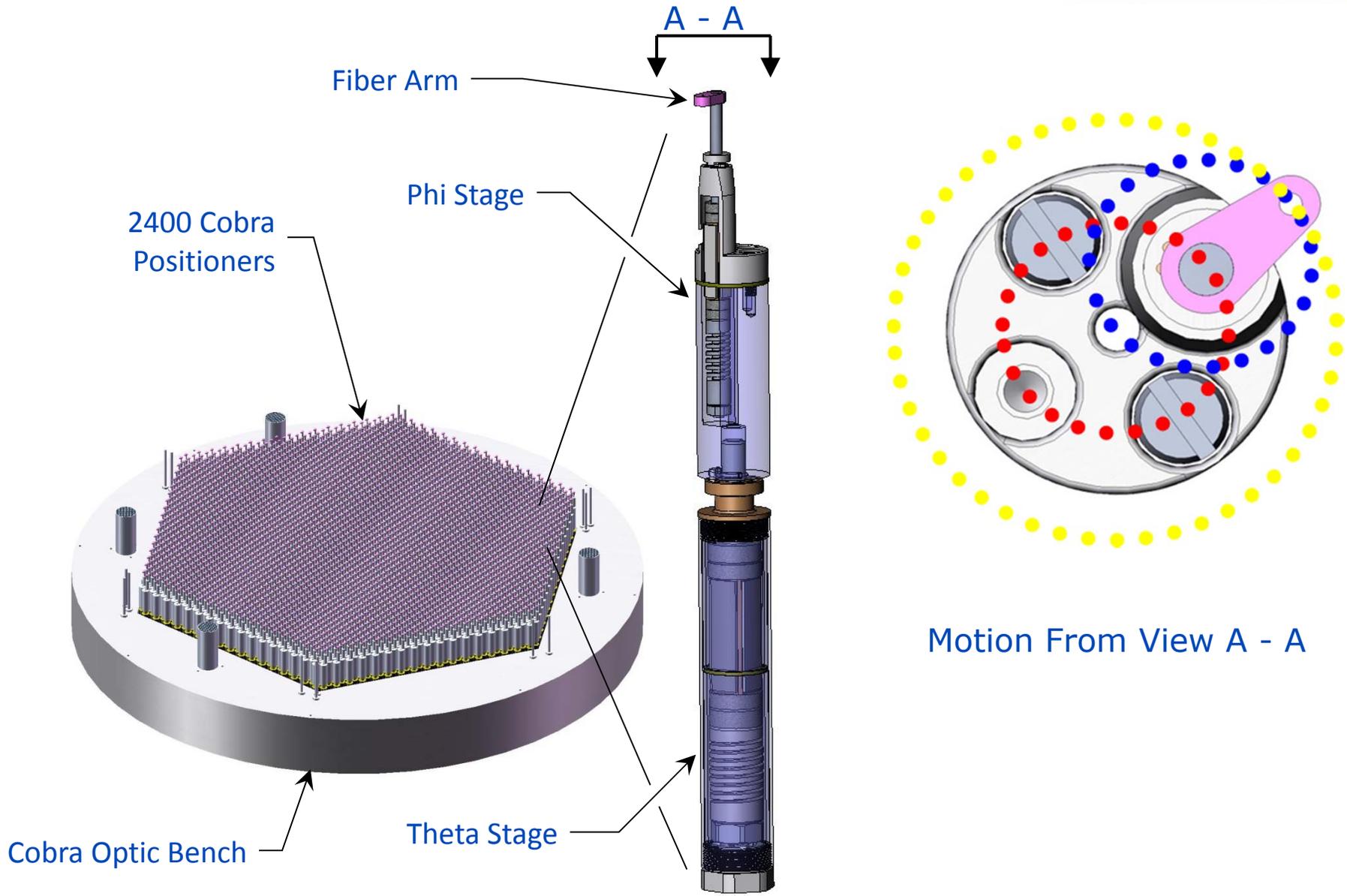
- This program started in 2008. Gen 1 positioners delivered in 2009.
Fisher, C., Braun D., Kaluzny, J., Haran, T., "Cobra – a Two-Degree of Freedom Fiber Optic Positioning Mechanism," IEEE Aerospace Conference paper #1185, Version 5 (2009).
- Gen 1A positioners delivered to JPL at the start of 2012.
- New Scale work is funded by the Jet Propulsion Laboratory, California Institute of Technology.
- JPL has received some funding from the Funding Program for World-Leading Innovative R&D on Science and Technology(FIRST) "Subaru Measurements of Images and Redshifts (SuMIRe)", CSTP, Japan.
- The New Scale Team: Justin Vacca, Rob Culhane, Conrad Hoffman, Dan Viggiano, Mat Wrona

System Requirements - PFS

- The Prime Focus Spectrograph (PFS) for the Subaru Telescope.
- Hex shaped array of 2394 fiber positioners in a 1.38 degree field of view at the prime focus of the telescope.
- Each 50 meter fiber is connected to a remote spectrograph
- Operating target:
 - 1 min to move the telescope
 - Reacquire new field of targets in 15 min
 - 45 fields to be observed per night.



System Requirements - PFS



System Requirements - PFS

Requirement	Value	Units
Positioner External Diameter	≤ 7.7	mm
1 st Stage Internal Diameter	≥ 1.2	mm
2 nd Stage Offset	2.375	mm
1 st Stage Hard Stop	≥ 360	deg
2 nd Stage Hard Stop	$\geq 180, < 360$	deg

Requirement	1 st Stage	2 nd Stage	Units
Step Size	$\leq .084$	$\leq .167$	deg
Stall Torque	≥ 346	≥ 337	$\mu\text{N-m}$
Speed	≥ 1.0	≥ 0.5	rev/sec

JPL has demonstrated moving a fiber within $5\mu\text{m}$ of an astronomical target using six move iterations with a success rate of 95%.

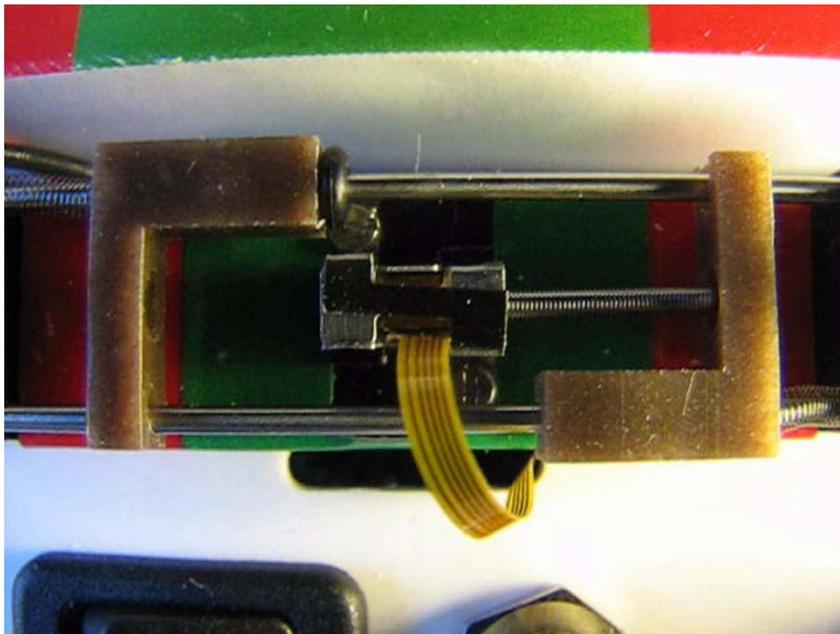


Motor Selection...Commercial Linear Motor



squigggle[®] **RV**
MOTORS

- PZT: multi-layer
- Voltage: 2.3-5.5 V
- No boost required
- Smart drive IC
- 5x smaller circuit
- Push: 30 g push
- Speed: 7 mm/sec
- Power: < 0.5 W



*US Patents (6,940,209),
(7,170,214), (7,309,943)
& (7,339,306)*

“Hula Hoop” vibrations
are directly converted
to linear movement

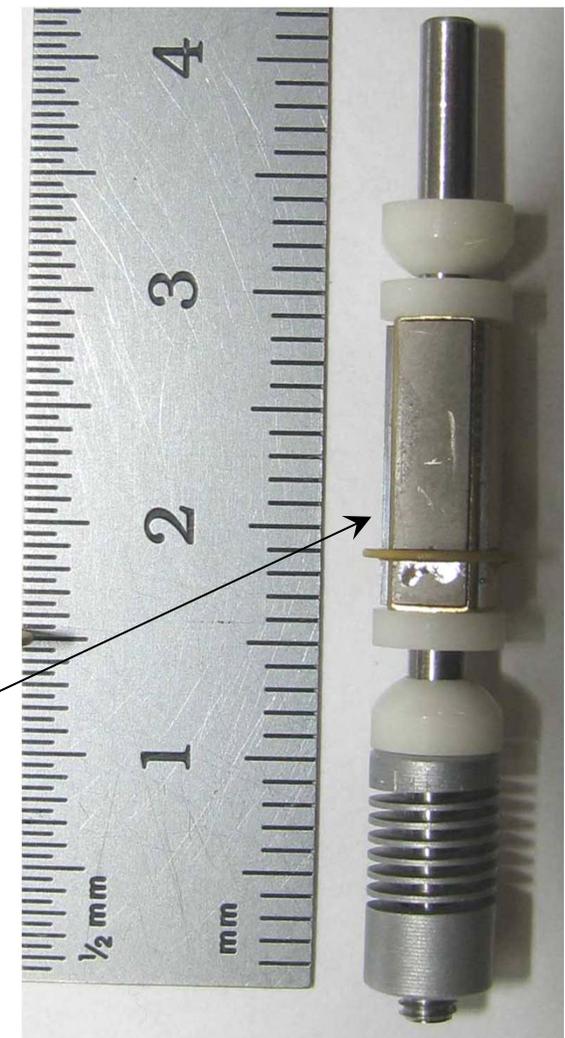
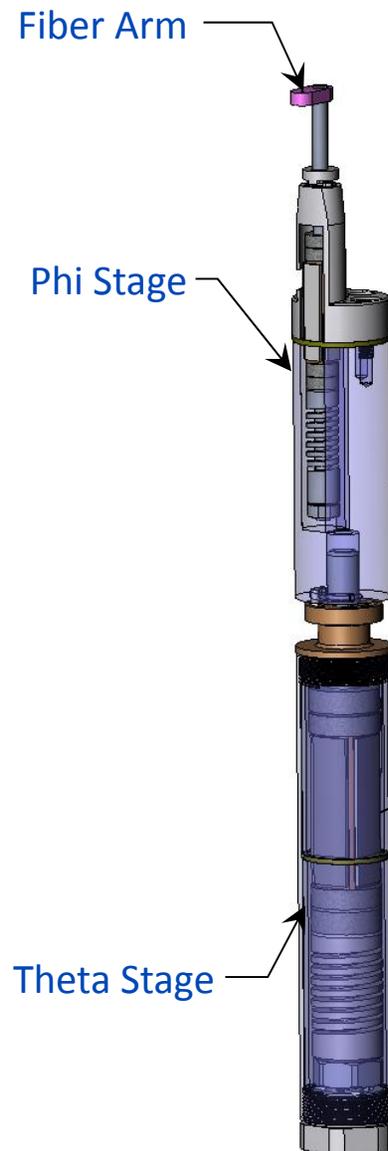
Motor Selection...Ultrasonic Rotary Motor

With thanks to:

W. Williams and W.J. Brown,
"Piezoelectric Motor", US Patent,
2439499, April 1948.

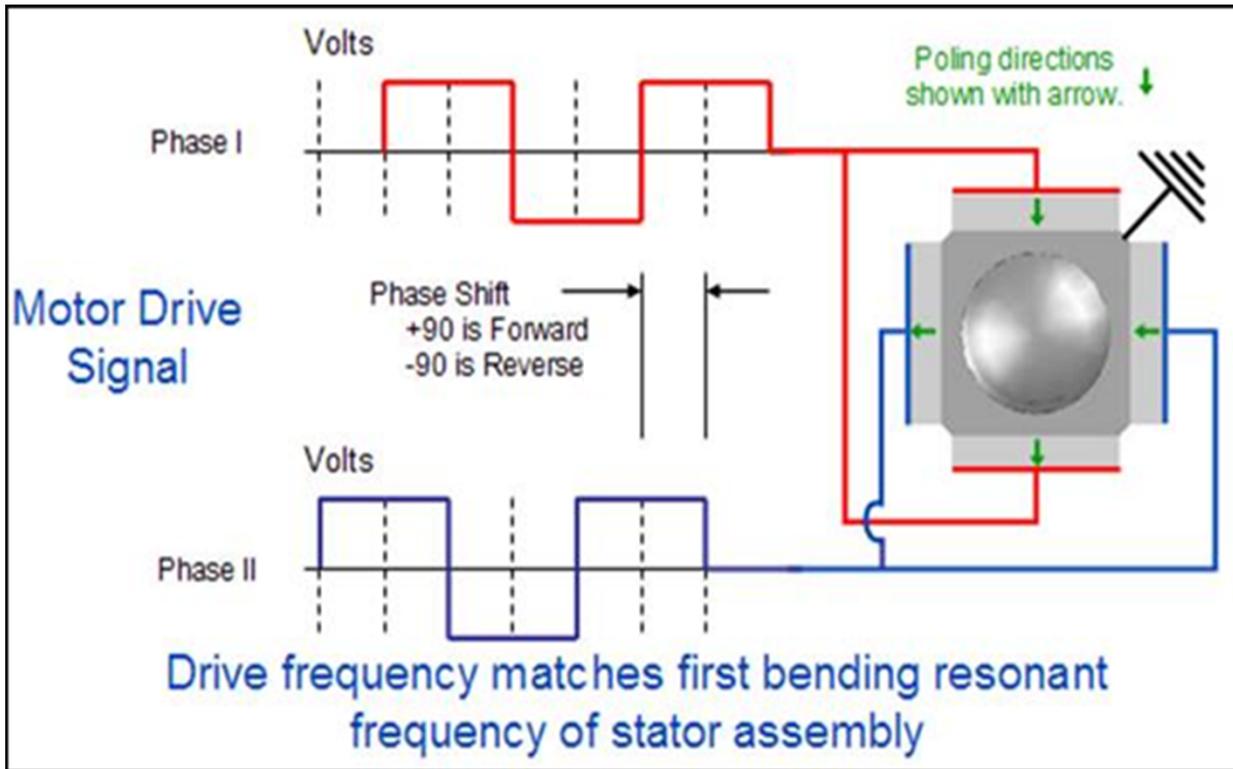
T. Morita et al, "An Ultrasonic Micro
Motor using a bending transducer
based on PZT thin film", Sensors and
Actuators A, Vol. 50, pp. 75-80,
1995.

B. Koc, S. Cagatay, K. Uchino, "A
piezoelectric motor using two
orthogonal bending modes of a
hollow cylinder", IEEE Trans.
Ultrasonic Ferroelectric Freq. Cont.
49, 495-500, 2002.



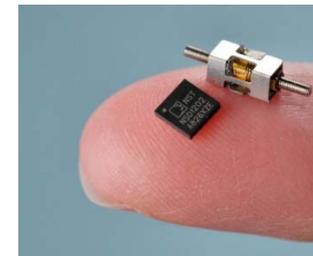
Theta stage motor

Motor Selection...Drive Details



MC-1100 (Today)
Size of Credit Card

Multi-Chip PCB
(2013)

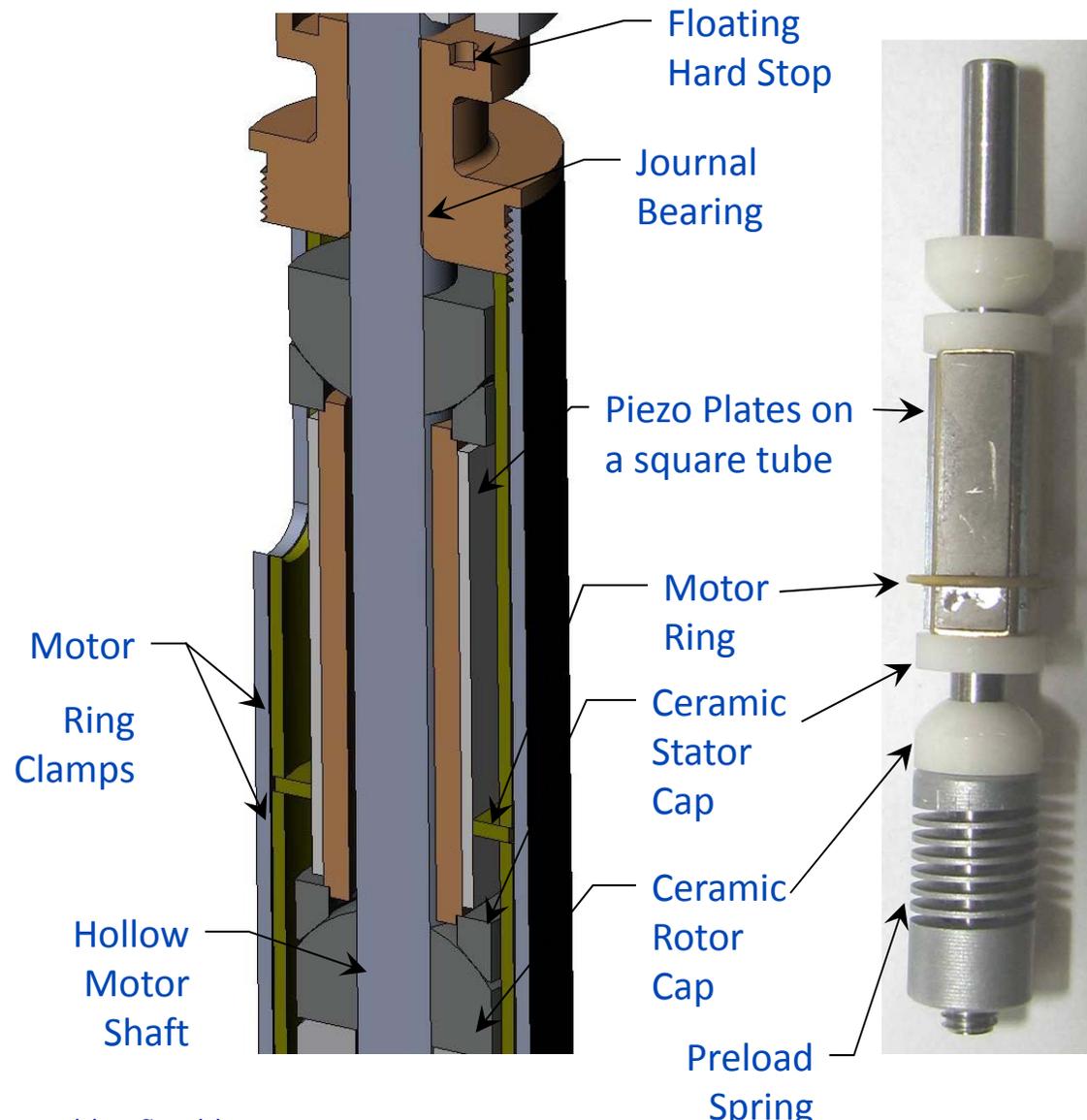


NSD2101 (> 2013)
Single-Chip Driver

Motor Selection...Details

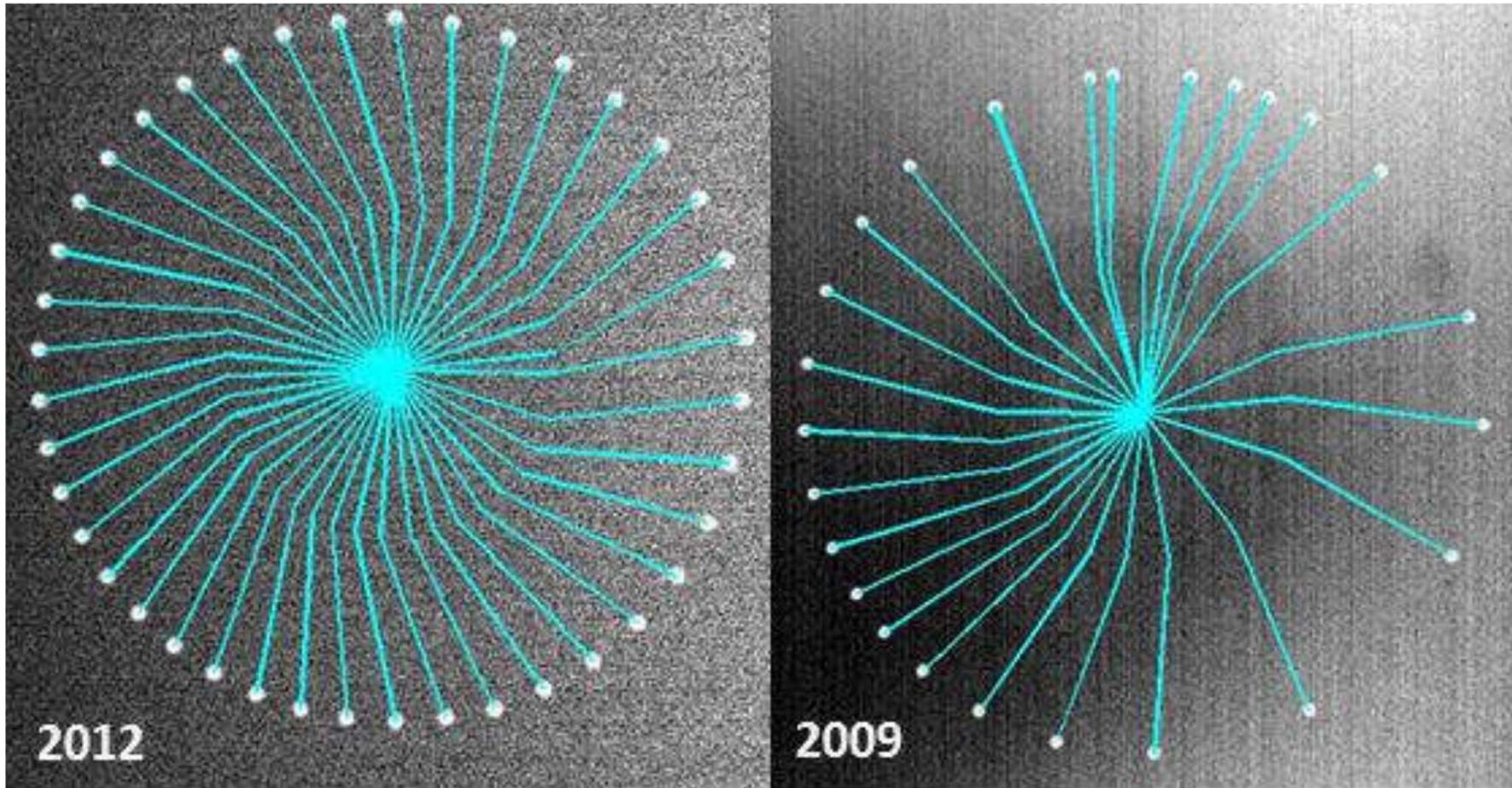
- High torque without gears.
- High resolution with zero backlash
- No lubrication.
- Hold position without power.
- Back-driveable without damage
- Journal bearing limits motor side loads
- Hard stops limit fiber twisting
- Motor step repeatability is sufficient to eliminate need for angle sensors.

All fiber positions are measured using backlit fibers and CCD camera.





2-Axis Positioner



JPL test results showing improvement in step precision and repeatability from Gen1 (2009) to Gen1A (2012)

1. Additional design improvements

- Further improve angular step repeatability.
- Keep the fiber aperture in the focal plane (+/- 50 μm) for all angles and positions.
 - Axes orthogonality and parallelism
 - Structural stiffness and bearing clearance
- To further reduce manufacturing cost.

2. Reduce size of drive electronics more than 70%

3. Deliver 60 positioners to JPL

4. Deliver > 2400 positioners to JPL.

Thank You

David Henderson, DHenderson@newscaletech.com